

ELEC 3106

Study Notes

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The University of New South Wales

NOTICE:

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NOTES - Week 2: Noise, distortion, saturation & dynamic range.

Noise: unwanted signals that obscure the desired signal.

- Johnson noise: a component generates a flat frequency noise voltage across its terminals. (white noise) (thermal noise)
- Shot noise: stems from fluctuating electric current, as discrete electric charges don't flow perfectly. Defined by formula:
 $I_{\text{noise}} (\text{rms}) = I_{\text{nr}} = (2qI_{\text{dc}}B)^{\frac{1}{2}}$ (B = bandwidth). Smaller currents have (relatively) larger fluctuations. It is Gaussian & white.
- $1/f$ noise: Oh, but there's more. Resistors suffer from fluctuations in resistance generating a 'pink' noise voltage and has a $\frac{1}{f}$ spectrum.
- Interference: many circuits are 'microphonic' they are sensitive to vibration and sound. May be controllable by shielding & filtering.

SIGNAL-TO-NOISE RATIO: $\text{SNR} = 10 \log_{10} \left(\frac{V_s^2}{V_n^2} \right) \text{ dB}$

If the signal is narrow-band the amp keeps adding noise power while signal power remains constant.

NOISE FIGURE: $\text{NF} = 10 \log_{10} \left(1 + \frac{V_n^2}{4kTR_s} \right)$

Ratio of output of the real amplifier to the output of an ideal amplifier of the same gain, with a R_s connected across the input terminals.

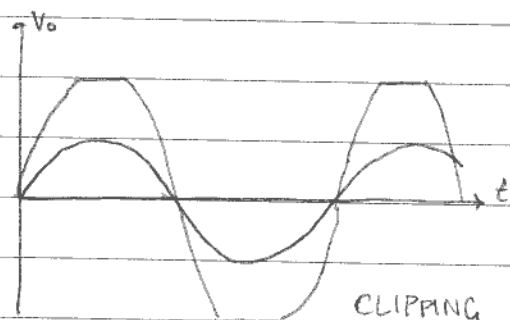
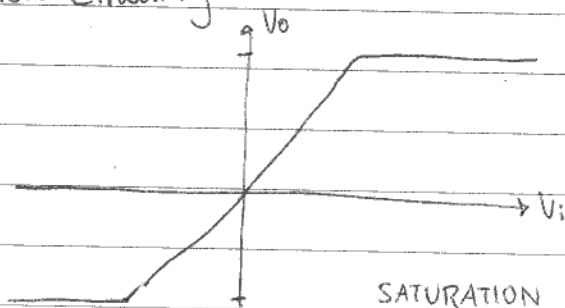
V_n^2 = mean squared noise voltage contributed by amplifier.

Dynamic Range: $\text{DR} = 20 \log \frac{\sqrt{V_{s^2 \text{max}}}}{\sqrt{V_n^2}}$

- upper limit - nonlinearity
- lower limit - noise.

Analogue equivalent to # bits. Ratio of max input level to min input level at which the system can sustain reasonable signal quality.

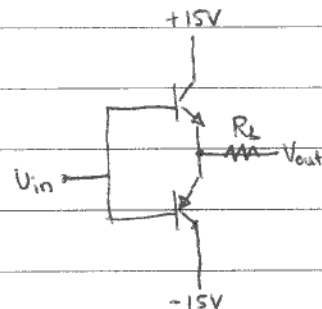
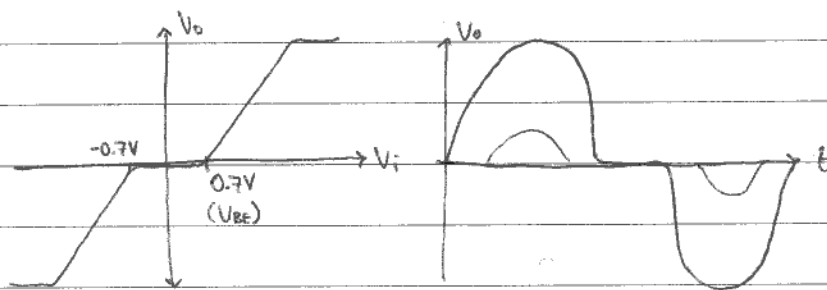
Non-Linearity:



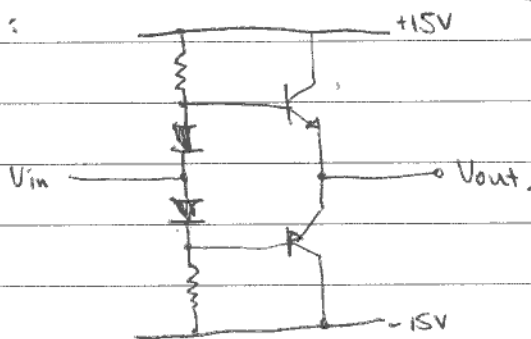
NOTES - Week 2: Noise, distortion, saturation & dynamic range.

Clipping is a form of waveform distortion generally occurring when overdriving an amplifier.

Crossover distortion - caused by switching between matched devices (transistors). The output trails the input with a drop of V_{BE} .

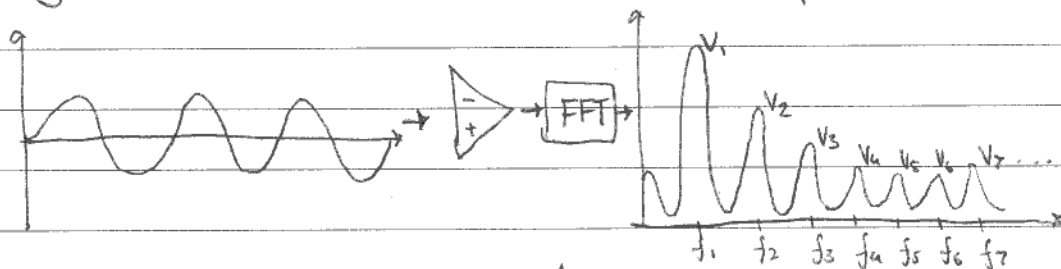


It can be alleviated with FEEDBACK (op-amp) or biasing the push-pull follower with diodes & resistors:

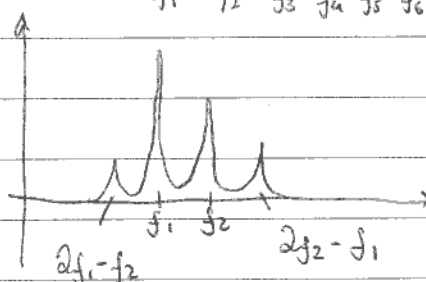


Measures of non-linearity: Total Harmonic Distortion.

- Apply a Fast Fourier Transform to a sine wave put through a broadband amp.



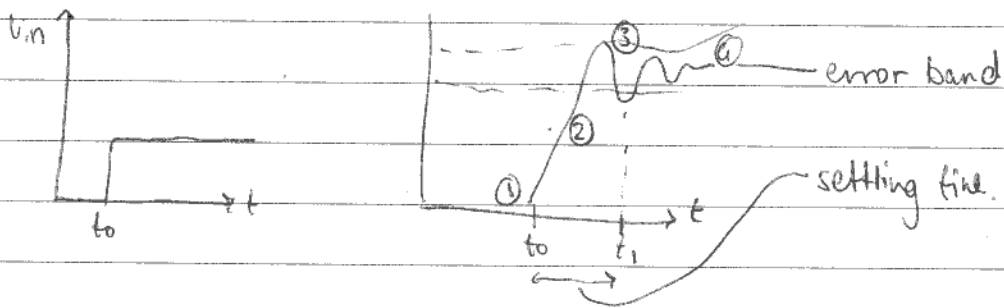
$$THD = \frac{\sqrt{V_2^2 + V_3^2 + V_4^2 \dots}}{V_1} \%$$



Third order intermodulation: after FFT

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Settling time: Time elapsed from the application of a step input to the point where the output settles to within a specified error band \rightarrow approaches the end.

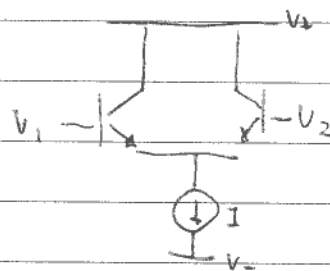
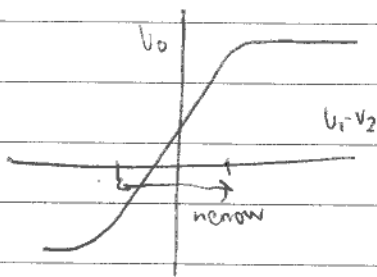


Settling time includes delay to the onset of output slewing, ① and slewing time ② and recovery time from slew over load, ③ and finally settling in the error band.

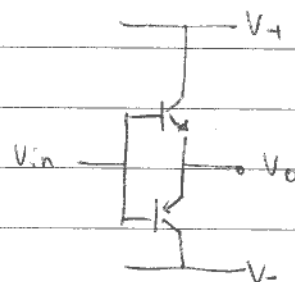
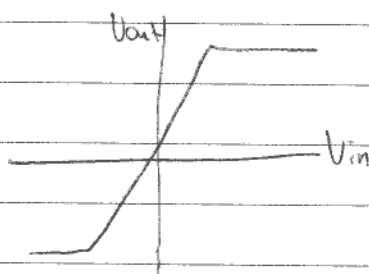
Consider ① Sample-and-hold circuits, and ② A/D converters.

Where are amplifiers non-linear?

1, Voltage transfer curve of input stage, typically differential.



2, Output stage VTC.



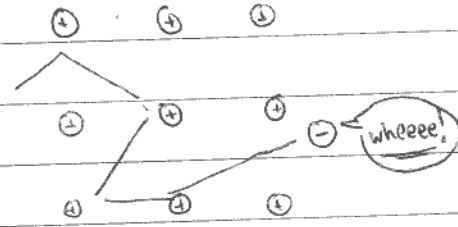
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Noise is often shown in 'spectral density'.

characterise noise by average, rms or mean square. Expressed in terms of spectral noise density. function of f .

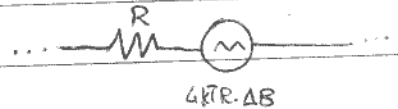
• Thermal noise:

caused by randomness in motion.
independent of frequency.



Noise models:

- Resistors $e_n^2 = \underbrace{4kTR}_{r^2/\text{Hz}} \cdot \underbrace{\Delta B}_{\text{bandwidth}}$ Boltzmann constant absolute temp



- ↳ No dependence on f
- ↳ Proportional to temperature & resistance.
- ↳ white (Johnson) noise

Nonlinear amplifiers: linear: $V_o = A_v V_{in}$

nonlinear: $V_o = A_1 V_{in} + A_2 V_{in}^2 + A_3 V_{in}^3 + \dots$

If V_{in} is a pure sinusoid, what would V_o look like?

• Let $V_{in} = a \cos(\omega t)$

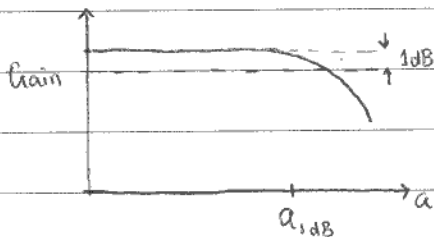
$$\therefore V_o = A_1 a \cos(\omega t) + A_2 a^2 \cos^2(\omega t) + A_3 a^3 \cos^3(\omega t)$$

$$= \frac{A_2 a^2}{2} + \left(A_1 a + \frac{3A_2 a^3}{4} \right) \cos(\omega t) + \frac{A_2 a^2}{2} \cos(2\omega t) - \frac{A_3 a^3}{4} \cos(3\omega t)$$

• These are n^{th} order harmonics generated by the non-linearity.

NOTES: Week 2: Noise, distortion, saturation & dynamic range

1dB Compression Point: the fundamental frequency component at output, that is the point where the device is outputting 1dB less power (say, 80%) is the 1dB compression point.



As amplitude increases, gain will surely decrease.

3rd order intermodulation:

- consider $V_{in} = a_1 \cos(\omega_1 t) + a_2 \cos(\omega_2 t)$, where ω_1 is close to ω_2 .
- consider amplifier with VTC: $V_o = A_1 V_{in} + A_2 (V_{in})^2$
- all kinds of frequency components are generated, including intermodulation.

(i) Fundamental components

$$(A_1 a_1 + \frac{3}{4} A_3 a_1^3 + \frac{3}{2} A_3 a_1 a_2^2) \cos(\omega_1 t)$$

$$(A_1 a_2 + \frac{3}{4} A_3 a_2^3 + \frac{3}{2} A_3 a_2 a_1^2) \cos(\omega_2 t)$$

(ii) Intermodulation products

$$@ \omega_1 \pm \omega_2 \rightarrow A_2 a_1 a_2 \cos(\omega_1 + \omega_2) t + A_2 a_1 a_2 \cos(\omega_1 - \omega_2) t$$

$$@ 2\omega_1 \pm \omega_2 \rightarrow \frac{3A_3}{4} a_1^2 a_2 \cos(2\omega_1 \pm \omega_2) t + \frac{3}{4} A_3 a_1^2 a_2 \cos(2\omega_1 \mp \omega_2) t$$

$$@ 2\omega_2 \pm \omega_1 \rightarrow \frac{3A_3 a_1 a_2^2}{4} \cos(2\omega_2 \pm \omega_1) t + \frac{3}{4} A_3 a_1 a_2^2 \cos(2\omega_2 \mp \omega_1) t$$

The 3rd order intermodulation products are $2\omega_1 - \omega_2$ and $2\omega_2 - \omega_1$, since ω_1 & ω_2 are very close to each other.

